

Many people have posted asking for some fool to give an example of protected mode programming, to allow everyone to laugh at their code.

Introduction

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I wrote my first protected mode program many years ago to learn all of the idiosyncracies of the Intel architecture. I still recommend this approach to anyone, because there's nothing like learning from your mistakes! But in the spirit of sharing knowledge, I offer my first program to all for edification and amusement. I am not saying it is good code, nor that it couldn't be done better, but since I was more interested in getting it to work than in doing it the best way, I believe this code is relatively straightforward.

Requirements

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I first had to work out what features I wanted to try - and being the fool I was I thought I'd try everything! This included:

- Accessing extended memory
- Multiple tasks
- Local descriptor tables
- Multiple privilege levels
- 16 and 32-bit code
- Revectoring hardware interrupts
- Direct hardware access (A20, PIC, timer, keyboard, screen etc.)
- Paging (although I dropped this for this program)

So this program is designed to start up multiple tasks, that each do the same thing - bounce a ball in its own window. If I could get it fast enough, they would seemingly all be able to bounce together.

High Level Design

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To make it easier on myself, I decided to effectively hard code as much as possible, letting the assembler do most of the work. This turned out to be a good idea, since I could have a look at the actual assembled constants and make sure I was telling it what I thought I was! My most invaluable tools at this stage were the '386 Intel manual, and Borland's TD - not to debug, but to have a look to the disassembled code. I even found a bug in Borland's disassembler!

So I wanted the program to do the following steps:

- Set up core system tables in preparation of the switch to protected mode
- Switch to protected mode
- Set up rest of system tables (esp. exception handlers)
- Set up each user task
- Twiddle thumbs while tasks ran, until user pressed <Esc>
- Return to real mode
- Restore system to DOS state

This last turned out to be invaluable, since having to reboot the computer every time to get out of my program wasted a lot of time (30 seconds reboot, 5 seconds running!). As it was, the system rebooted itself more than enough times until I got the exception handlers right!

Lessons I Learned

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To help any other novice protected-mode programmers out there, I can recommend the following:

- 1) Spend the time to set up exception handlers. It is so easy to make a mistake that merely dumping all of the register contents onto the screen (in hex) is invaluable for not only finding which instruction caused the problem, but also in finding out what error the '386 is complaining about. If you don't do this step, the most likely scenario is that any exception will result in another, which will result in a double exception, which will result in another exception, which will shut down the CPU, which will reboot the computer.
- 2) Examine the listing file the assembler can produce. Make sure the assembler

and you both think you're talking about the same thing! Use a debugger (unfortunately DOS's DEBUG only accepts 8086 instructions) and type in the assembled hex bytes, and see if the debugger thinks it's the same instruction as you've typed. (Even this isn't perfect - the debugger may be assuming you're in 16-bit mode for a 32-bit instruction, producing wierd results! It also may have bugs itself!)

Idiosyncracies I Discovered

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- 1) Protected mode far jumps can't be assembled. Borland's TASM (anyway) can't be convinced to assemble JMP OFFSET ProtMode:OFFSET ProtProc. So I had to dummy these up with DBs and DWs.
- 2) The '386 does not save a task's LDT into its TSS on a task switch. So if LDT changes, you either have to update the TSS manually, or prevent task switching.
- 3) The Trace bit in the TSS is not automatically switched off when the task is entered. This means that if tasks are still being switched behind the debugger, the T bit needs to be switched off manually to prevent re-entering the debugger!

Tools I Used

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I have assembled this program with three different version of Borland's TASM. I don't own MASM, but I do not believe I have done anything Borland specific. If anyone has any trouble, contact me and I will try to fix it.

The Code

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I have had trouble attaching text to News articles so that everyone can decode the result. I also do not have the facilities to put it in an ftp site. If anyone wants to mail me I'll deliver the complete source to them so that they can do it for me. For now I will post the code in long-hand, in five parts (~300 lines per part), and I will thread them off this message so that it doesn't clutter the Newsgroup.

Part 1 - Definitions

Part 2 - Real mode entry point

Part 3 - Protected mode entry point

Part 4 - User code (small)

Part 5 - Interrupt and exception handlers (large)

WARNINGS (One legal, one moral)

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As a professional programmer, I identify with my code. This may be old, and not how I do things now, but it is still mine. I don't mind showing this code to others so that they can learn, and you can experiment to your heart's content, but DO NOT USE ANY PART of this code in new software, whether commercial or otherwise.

Finally, this code is the ultimate in unfriendliness! It assumes that the whole machine belongs to it - including ALL RAM. This means that it should be run on a vanilla system - no HIMEM.SYS, no memory managers, and DEFINITELY no disk-cache programs! Your memory WILL be written over!

John Burger

```

;*****
; Copyright (c) John Burger, 1990-1995. All rights reserved.
; This code has been placed in the public domain by John Burger for example
; purposes only - to demonstrate various techniques for programming the
; Intel 80386 et. al. in protected mode. It is available for other people to
; experiment with, NOT to include in other software, whether commercial or
; otherwise.
;*****

; This program switches into protected mode (on a '386+), starts many tasks
; that all do the same thing in different windows, and continues until the
; <Esc> key is pressed and released.
;
; Minimum system: '386 with 2Mb RAM (to test A20 line)
;                  Standard A20 line
; If A20 line non-standard, or <2Mb RAM available, modify the code to use DOS
; RAM rather than extended RAM.
;
; *** WARNING ***
; System should be 'vanilla': No HIMEM.SYS, memory manager or disk cache.
; This program accesses the hardware directly, and will TRASH any memory-
; manager by writing all over it!
;
; Experiments to try:
; - Various values for WindowWidth and WindowHeight:
;   0,0 maximises number of tasks;
; - Various values for SecTick to slow down and speed up operation:
;   Below 19 and above 65535 will cause compiler errors.
;   Higher values may cause GP faults!
; - Insert an INT 3 anywhere in ProtSeg, BallCode or IntCode.
; - Insert any INT in the above segments, AFTER they've been set up.
;   Look for *** in ProtSeg
; - Modify code to generate various exceptions:
;   Crash the stack (MOV SP,1; PUSH AX)
;   Access illegal memory (INC BYTE PTR ES:[0FFFFFFFh])
;   Invalid op-codes (LOCK XOR AX,AX)
;   Enable single-step debugging (PUSHF; POP AX; OR AX,100h; PUSH AX; POPF)
;   The single-step debug handler simply waits for the user to press
;   <Enter> or <Space>, then returns. To indicate waiting, it uses a
;   "ding!" in the top right corner of the screen. Pressing <Enter>
;   stops tracing.
;
;
; WARN                                ; Listen to every assembler complaint!
;
; .386P                               ; Going to be doing 386 Prot Mode inst
;
;
; Stack segment, reserved by DOS but used in protected mode also.
;
StackSeg SEGMENT STACK PARA USE32      ; DOS stack
        DB 100 DUP ('STACK ')         ; (Used to ID memory)
StackTop EQU $                          ; For 16 bit code
StackSeg ENDS

StackSize EQU 1024                      ; For 32 bit stacks
;
; Multitasking constants:
; Reduce SecTick for slower machines.
; Note certain values may cause errors.
; Change WindowWidth and WindowHeight to change number of windows.
; Note certain values may cause errors.
; Change BounceTime to slow down the bouncing.
; Change Ball to change character that bounces.
;
SecTick EQU 1000                        ; Task switches per second

```

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WindowWidth EQU 4 ; Width of a window
WindowHeight EQU 3 ; Height of a window
BounceTime EQU 1 ; Time delay before moving
Ball EQU 1 ; Character to bounce

;=====
;
; System constants. These are defined by the hardware.
;
ClockFreq EQU 1193200 ; Timer 0 frequency

; Constants in Granular byte of descriptor table entry
PageGran EQU 80h
ByteGran EQU 00h
More64K EQU 40h
Less64K EQU 00h
LargeAddr EQU 40h
SmallAddr EQU 00h
Available EQU 10h
LimitHi EQU 0Fh

; Constants in Type byte of descriptor table entry
Present EQU 80h
NotPresent EQU 00h
DPL EQU 60h
Privilege0 EQU 00h
Privilege1 EQU 20h
Privilege2 EQU 40h
Privilege3 EQU 60h
Memory EQU 10h
System EQU 00h
Execable EQU 08h
NotExecable EQU 00h
Gate386 EQU 08h
Gate286 EQU 00h
ExpandDown EQU 04h
ExpandUp EQU 00h
Conform EQU 04h
NonConform EQU 00h
Writable EQU 02h
NotWritable EQU 00h
Readable EQU 02h
NotReadable EQU 00h
Accessed EQU 01h
NotAccessed EQU 00h

; Bit indicating descriptor is in LDT
LocalDT EQU 04h

; Descriptor types
AvailTSS EQU 1
LDT EQU 2
BusyBit EQU 2
BusyTSS EQU 3
CallGate EQU 4
TaskGate EQU 5
IntGate EQU 6
TrapGate EQU 7

Int386 EQU Present+Gate386+IntGate ; Disable ints within routine
Trap386 EQU Present+Gate386+TrapGate ; Keep ints
Task386 EQU Present+TaskGate ; Not Gate386 - not defined!

;=====
;
; System structures. These are defined by the hardware.
;

```

```

; Descriptor structure
Descriptor STRUC
LimitLo    DW      ?
BaseLo     DW      ?
BaseMid    DB      ?
DescType   DB      ?
DescGran   DB      ?
BaseHi     DB      ?
Descriptor ENDS

```

```

; Gate structure
Gate       STRUC
OffsetLo   DW      ?
Selector   DW      ?
Count      DB      ?
GateType   DB      ?
OffsetHi   DW      ?
Gate       ENDS

```

```

; Pseudo-descriptor table pointer (GDT/IDT)
DTPtr      STRUC          ; Descriptor Table Pointer
Limit      DW      ?
Base       DD      ?
DTPtr      ENDS

```

```

; =====
; System segments. The structure of these is defined by the hardware.

```

```

;
; Interrupt Descriptor Table.
; Intel has reserved the first 32 interrupts, and given the first half of them
; functions. Note that hardware vectors have been moved!
; Since it is such a small program (ha!), the entire table can be hard-coded
; here. Note that the descriptor fields are simply offsets into the GDT.
; Note also that four faults are represented by their own tasks, as
; recommended by Intel - Debug, Double, BadTSS, and BadStack. These all
; guarantee that a valid state will be available to the system to process the
; fault.

```

```

;
IDT        SEGMENT        PARA USE16
Divide     Gate           <OFFSET DivideInt,OFFSET IntCode,0,Trap386,0>
;Debug     Gate           <0,OFFSET DebugTSS,0,Task386,0> ; Debug as separate task?
Debug      Gate           <OFFSET DebugInt,OFFSET IntCode,0,Trap386,0>
NMI        Gate           <OFFSET NMIIInt,OFFSET IntCode,0,Trap386,0>
Break      Gate           <OFFSET BreakInt,OFFSET IntCode,0,Trap386,0>
Overflow   Gate           <OFFSET OverInt,OFFSET IntCode,0,Trap386,0>
OutBound   Gate           <OFFSET BoundInt,OFFSET IntCode,0,Trap386,0>
InvalidOp  Gate           <OFFSET OpInt,OFFSET IntCode,0,Trap386,0>
No387      Gate           <OFFSET No387Int,OFFSET IntCode,0,Trap386,0>
Double     Gate           <0,OFFSET DoubleTSS,0,Task386,0>
Over387    Gate           <OFFSET Over387Int,OFFSET IntCode,0,Trap386,0>
BadTSS     Gate           <0,OFFSET BadTSSTSS,0,Task386,0>
NoSegment  Gate           <OFFSET NoSegInt,OFFSET IntCode,0,Trap386,0>
BadStack   Gate           <0,OFFSET StackTSS,0,Task386,0>
General    Gate           <OFFSET GenInt,OFFSET IntCode,0,Trap386,0>
PageFault  Gate           <OFFSET PageInt,OFFSET IntCode,0,Trap386,0>
           Gate           <OFFSET Int15,OFFSET IntCode,0,Trap386,0>
Bad387     Gate           <OFFSET Bad387Int,OFFSET IntCode,0,Trap386,0>
           Gate           <OFFSET Int17,OFFSET IntCode,0,Trap386,0>
           Gate           <OFFSET Int18,OFFSET IntCode,0,Trap386,0>
           Gate           <OFFSET Int19,OFFSET IntCode,0,Trap386,0>
           Gate           <OFFSET Int20,OFFSET IntCode,0,Trap386,0>
           Gate           <OFFSET Int21,OFFSET IntCode,0,Trap386,0>
           Gate           <OFFSET Int22,OFFSET IntCode,0,Trap386,0>
           Gate           <OFFSET Int23,OFFSET IntCode,0,Trap386,0>
           Gate           <OFFSET Int24,OFFSET IntCode,0,Trap386,0>
           Gate           <OFFSET Int25,OFFSET IntCode,0,Trap386,0>
           Gate           <OFFSET Int26,OFFSET IntCode,0,Trap386,0>

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        Gate      <OFFSET Int27,OFFSET IntCode,0,Trap386,0>
        Gate      <OFFSET Int28,OFFSET IntCode,0,Trap386,0>
        Gate      <OFFSET Int29,OFFSET IntCode,0,Trap386,0>
        Gate      <OFFSET Int30,OFFSET IntCode,0,Trap386,0>
        Gate      <OFFSET Int31,OFFSET IntCode,0,Trap386,0>
Timer      Gate      <OFFSET TimerInt,OFFSET IntCode,0,Int386,0>
Keyboard   Gate      <OFFSET KeyInt,OFFSET IntCode,0,Int386,0>
Slave      Gate      <OFFSET SlaveInt,OFFSET IntCode,0,Int386,0>
COM2       Gate      <OFFSET COM2Int,OFFSET IntCode,0,Int386,0>
COM1       Gate      <OFFSET COM1Int,OFFSET IntCode,0,Int386,0>
        Gate      <OFFSET IRQ5,OFFSET IntCode,0,Int386,0>
        Gate      <OFFSET IRQ6,OFFSET IntCode,0,Int386,0>
Printer    Gate      <OFFSET PrintInt,OFFSET IntCode,0,Int386,0>
        Gate      <OFFSET IRQ8,OFFSET IntCode,0,Int386,0>
        Gate      <OFFSET IRQ9,OFFSET IntCode,0,Int386,0>
        Gate      <OFFSET IRQ10,OFFSET IntCode,0,Int386,0>
        Gate      <OFFSET IRQ11,OFFSET IntCode,0,Int386,0>
        Gate      <OFFSET IRQ12,OFFSET IntCode,0,Int386,0>
        Gate      <OFFSET IRQ13,OFFSET IntCode,0,Int386,0>
        Gate      <OFFSET IRQ14,OFFSET IntCode,0,Int386,0>
        Gate      <OFFSET IRQ15,OFFSET IntCode,0,Int386,0>
IDTLimit   EQU      $-1
IDT         ENDS

```

```

;
; Global Descriptor Table.
;
; None of the Base fields can be filled in, as it is not know where the code
; will load into memory.
;
; Only the first entry is reserved by Intel. This is the unused descriptor to
; allow the system to detect null pointer references.
; The others are arbitrary.
; The two MSDOS ones are for the return to DOS - to reset the descriptors back
; to valid values.
; GDTData and IDTData are aliases for the GDT and IDT respectively.
; ProtCode is the protected-mode code segment for intialisation and wrapup.
; IntCode is the protected-mode code segment for interrupt code. (32-bit)
; Screen is the CGA/EGA/VGA/SVGA text screen.
; MainTask is the task state segment of the executive.
; MainStack is the level 0 stack for the main task.
; StackTSS is the task state segment for a stack fault.
; TSSStack is the stack for the stack fault task.
; BadTSSTSS is the task state segment for a TSS fault.
; BTStack is the stack for the BadTSS fault task.
; DoubleTSS is the task state segment for a double fault.
; DblStack is the stack for the double fault task.
; DebugTSS is the task state segment for the debug trap.
; DbgStack is the stack for the debug trap task.
; More is the room for all of the TSSs and LDTs of the user tasks.
;
GDT      SEGMENT   PARA USE16
        Descriptor<>
MSDOSCode Descriptor<0FFFFh,?,?,Present+Memory+Execable+Readable,ByteGran,0>
MSDOSData Descriptor<0FFFFh,?,?,Present+Memory+Writable,ByteGran,0>
GDTData   Descriptor<GDTLimit,?,?,Present+Memory+Writable,ByteGran,0>
IDTData   Descriptor<IDTLimit,?,?,Present+Memory+Writable,ByteGran,0>
ProtCode  Descriptor<ProtLimit,?,?,Present+Memory+Execable+Readable,ByteGran,0>
IntCode   Descriptor<IntLimit,?,?,Present+Memory+Execable+Readable,ByteGran+LargeAddr,0>
Screen    Descriptor<3999,8000h,0Bh,Present+Privilege3+Memory+Writable,ByteGran,0>
StackTSS  Descriptor<TSSLimit,?,?,System+Gate386+AvailTSS,ByteGran,0>
TSSStack  Descriptor<StackTop-1,?,?,Present+Memory+Writable,ByteGran+More64K,0>
BadTSSTSS Descriptor<TSSLimit,?,?,System+Gate386+AvailTSS,ByteGran,0>
BTStack   Descriptor<StackTop-1,?,?,Present+Memory+Writable,ByteGran+More64K,0>
DoubleTSS Descriptor<TSSLimit,?,?,System+Gate386+AvailTSS,ByteGran,0>
DblStack  Descriptor<StackTop-1,?,?,Present+Memory+Writable,ByteGran+More64K,0>
DebugTSS  Descriptor<TSSLimit,?,?,System+Gate386+AvailTSS,ByteGran,0>
DbgStack  Descriptor<StackTop-1,?,?,Present+Memory+Writable,ByteGran+More64K,0>

```

```

MainTask Descriptor<TSSLimit,?,?,Present+System+Gate386+AvailTSS,ByteGran,0>
MainStack Descriptor<StackTop-1,?,?,Present+Memory+Writable,ByteGran+More64K,0>
UserTasks EQU $
          ORG 0FFFFh
GDTLimit EQU $
GDT      ENDS

```

```

;
; Task State Segment.
; The structure is defined by Intel. Note multiple TSSs will be created.
;

```

```

TSS      SEGMENT      PARA USE16
BackLink DW 0
          DW 0
ESP0     DD 0
SS0      DW 0
          DW 0
ESP1     DD 0
SS1      DW 0
          DW 0
ESP2     DD 0
SS2      DW 0
          DW 0
PDBR     DD 0                      ; Page Directory Base Register
EIPReg   DD ?
EFlags   DD ?
EAXReg   DD ?
ECXReg   DD ?
EDXReg   DD ?
EBXReg   DD ?
ESPReg   DD ?
EBPReg   DD ?
ESIReg   DD ?
EDIReg   DD ?
ESSeg    DW ?
          DW 0
CSSeg    DW ?
          DW 0
SSSeg    DW ?
          DW 0
DSSeg    DW ?
          DW 0
FSSeg    DW ?
          DW 0
GSSeg    DW ?
          DW 0
LDTR     DW 0                      ; Local Descriptor Table Register
          DW 0
Tracing  DW 0
IOMapBase DW TSSSize
TSSSize  EQU $-BackLink
TSSLimit EQU TSSSize-1
TSS      ENDS

; Debugger TSS
TSSDebug SEGMENT      PARA USE16
          DB TSSSize DUP (?)
TSSDebug ENDS

; Double TSS
TSSDouble SEGMENT      PARA USE16
          DB TSSSize DUP (?)
TSSDouble ENDS

; Bad TSS TSS
TSSTSS   SEGMENT      PARA USE16
          DB TSSSize DUP (?)
TSSTSS   ENDS

```

```

; Bad Stack TSS
BadStackTSS SEGMENT PARA USE16
    DB    TSSSize DUP (?)
BadStackTSS ENDS

;
; Local Descriptor Table.
; Each user gets their own LDT, with a descriptor for:
; Stack0:    level 0 stack
; Stack3:    level 3 stack (levels 1 and 2 not used)
; TaskCode:  user code segment - all user code is in the same segment
; TaskData:  user data segment - all user data is in a private segment
;
TaskLDT    SEGMENT    PARA USE16
Stack0     Descriptor<>
Stack3     Descriptor<>
TaskCode   Descriptor<>
TaskData   Descriptor<>
LDTLimit   EQU        $-1
TaskLDT    ENDS

; DOS/Protected mode data
Data       SEGMENT    PARA USE16
OldIDT     DTPtr      <>                ; Old (DOS) IDT value
GDTPtr     DTPtr      <GDTLimit,?>      ; GDT pointer constructed here
IDTPtr     DTPtr      <IDTLimit,?>      ; IDT pointer constructed here
Corner     DW          0101h            ; The starting window corner
TaskJump   LABEL      PWORD            ; This is the task jump address
           DD          0                ; The offset part is unused
NextTask   DW          0                ; The next task to run
LastTask   DW          0                ; The last task in the GDT
KeyPress   DB          0                ; A one-key buffer!
TaskLock   DB          0                ; When 1, do NOT task switch!
Data       ENDS

```

Burger / John Adriaan (ISE) <u86...@student.canberra.edu.au> wrote:

>The Code

>=====

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>the result. I also do not have the facilities to put it in an ftp site. If
>anyone wants to mail me I'll deliver the complete source to them so that they
>can do it for me. For now I will post the code in long-hand, in five parts
>(~300 lines per part), and I will thread them off this message so that it
>doesn't clutter the Newsgroup.

>

>Part 1 - Definitions

>Part 2 - Real mode entry point

>Part 3 - Protected mode entry point

>Part 4 - User code (small)

>Part 5 - Interrupt and exception handlers (large)

I knew I was forgetting something, but I couldn't remember what it was!
It hit. To assemble the above, get it all into one file in the above order.
Then simply assemble it with

TASM PROTMODE (or whatever assembler you use - no DEFINES needed)

then

TLINK /3 PROTMODE (or whatever. There are 32-bit fixups: Borland uses /3)

The result is a 69K-odd .EXE, 4K of which is the code, 64K is the GDT!

```

;=====
;
; This is the DOS code segment, that starts and stops the program.
;

RealSeg    SEGMENT    PARA USE16

            ASSUME     CS:RealSeg,DS:Nothing,ES:Nothing,FS:Nothing,GS:Nothing

Entry      PROC        FAR
;
; Initialise.
;
            MOV        AH,1                ; Set cursor size
            MOV        CX,2607h           ; to invisible!
            INT        10h                ; using BIOS

            MOV        AX,SEG Data        ; Point FS to data
            MOV        FS,AX
            ASSUME     FS:Data            ; And tell assembler

            MOV        AX,SEG GDT         ; Point DS to GDT
            MOV        DS,AX
            ASSUME     DS:GDT             ; And tell assembler

            SIDT        FS:[OldIDT]       ; Store old IDT pointer (for recall)

;
; Initialise GDT base entries.
;
            XOR        EAX,EAX            ; Zero EAX
            MOV        AX,SEG RealSeg     ; Get start segment into AX
            MOV        BX,OFFSET MSDOSCode ; Point to GDT entry
            CALL        StoreDesc         ; And update GDT

            MOV        AX,SEG Data        ; Get data segment into AX
            MOV        BX,OFFSET MSDOSData ; Point to GDT entry
            CALL        StoreDesc         ; And update GDT

            MOV        AX,SEG ProtSeg     ; Get Prot code segment into AX
            MOV        BX,OFFSET ProtCode ; Point to GDT entry
            CALL        StoreDesc         ; And update GDT

            MOV        AX,SEG IntSeg      ; Get Int segment into AX
            MOV        BX,OFFSET IntCode  ; Point to GDT entry
            CALL        StoreDesc         ; And update GDT

            MOV        AX,SEG StackSeg    ; Get Stack segment into AX
            MOV        BX,OFFSET MainStack ; Point to GDT entry
            CALL        StoreDesc         ; And update GDT

            MOV        AX,SEG GDT         ; Get GDT segment into AX
            SHL        EAX,4              ; Turn into linear address
            MOV        FS:[GDTPtr.Base],EAX ; Store into GDT pointer
            MOV        BX,OFFSET GDTData  ; Point to GDT entry
            CALL        StoreLin          ; And update GDT

            MOV        AX,SEG IDT         ; Get IDT segment into AX
            SHL        EAX,4              ; turn into linear address
            MOV        FS:[IDTPtr.Base],EAX ; Store into IDT pointer
            MOV        BX,OFFSET IDTData  ; Point to GDT entry
            CALL        StoreLin          ; And update GDT

            MOV        AH,0DFh            ; Enable A20 line
            CALL        GateA20           ; Call Gate routine
            JNZ        FailA20            ; Didn't work! Bomb!
            LGDT        FS:[GDTPtr]       ; Point to GDT

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        LIDT      FS:[IDTPtr]          ; Point to IDT

        MOV      EAX,CR0              ; Get current CR0
        OR       EAX,1                ; Set Protected Mode bit
        MOV      CR0,EAX              ; NOW IN PROTECTED MODE!

; Getting the assembler to assemble a protected mode jump with the correct
; segment and offset is next to impossible. So just hard-code it!

        DB       0EAh                ; JMP FAR ProtCode:ProtMode
        DW       OFFSET ProtMode,OFFSET ProtCode

; Jump back here to return to real mode.

BackReal:
        XOR      AX,AX                ; No Local Descriptor Table
        LLDT     AX
        MOV      AX,OFFSET MSDOSData  ; Reload ALL segment registers
        MOV      DS,AX                ; to point them to DOS-type
        MOV      ES,AX                ; segments
        MOV      FS,AX
        MOV      GS,AX
        MOV      SS,AX
        MOV      SP,0FFFEh           ; Just temporary, I promise!
        MOV      EAX,CR0              ; Get current CR0
        AND      EAX,NOT 1            ; Reset protected mode bit
        MOV      CR0,EAX              ; Back in real mode

;
; Now the trick is getting the assembler to assemble a FAR jump to the
; next instruction! It always optimises it out! So hard-code it again.
;
        DB       0EAh
        DW       OFFSET RealMode,SEG RealSeg ; JMP FAR RealSeg:RealMode

RealMode:
        MOV      AX,SEG StackSeg       ; Put stack back
        MOV      SS,AX
        MOV      SP,OFFSET StackTop    ; SP too
        MOV      AX,SEG Data           ; Re-reload all segment registers
        MOV      DS,AX                 ; in real mode
        MOV      ES,AX
        MOV      FS,AX
        MOV      GS,AX
        ASSUME   DS:Data,ES:Nothing,FS:Nothing,GS:Nothing ; Tell assembler
        LIDT     [OldIDT]              ; Restore IDT pointer

;
; Restore timer back to 18.2 times a second
;
        MOV      AL,0                  ; Divisor for ssllllllooooooww!
        OUT      40h,AL                ; Low byte
        JMP      $+2                   ; (tap foot)
        OUT      40h,AL                ; High byte

;
; Restore Priority Interrupt Controllers (PICs) to DOS expectations
;
        MOV      AL,11h                ; Initialise PICs
        OUT      20h,AL
        OUT      0A0h,AL

        MOV      AL,08h                ; PIC1 @ Int 08h
        OUT      21h,AL
        MOV      AL,70h                ; PIC2 @ Int 70h
        OUT      0A1h,AL

        MOV      AL,00000100b          ; PIC1 has slave on IRQ2
        OUT      21h,AL

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        MOV     AL,02h                ; PIC2 is slaved to IRQ2
        OUT     0A1h,AL

        MOV     AL,01h                ; 80x86 mode
        OUT     21h,AL
        OUT     0A1h,AL

        MOV     AL,00h                ; Enable all interrupts
        OUT     21h,AL
        OUT     0A1h,AL

        MOV     AH,0DDh               ; Restore A20 line
        CALL    GateA20

FailA20:
        STI
        MOV     AH,1                  ; Restore cursor
        MOV     CX,0607h
        INT     10h
        MOV     AH,2                  ; Cursor to bottom of screen
        MOV     BH,0
        MOV     DX,1700h
        INT     10h
        MOV     AX,4C00h              ; Exit program
        INT     21h

Entry    ENDP

StoreDesc PROC    NEAR
        SHL     EAX,4                ; Turn into linear address
StoreLin:
        MOV     [BX.BaseLo],AX       ; Store into GDT
        SHR     EAX,16               ; Get high part of EAX
        MOV     [BX.BaseMid],AL      ; And store
        RET
StoreDesc ENDP

GateA20  PROC    NEAR
        CLI                ; Critical code!
        CALL    Wait8042    ; Wait for it to be ready
        JNZ     SHORT Dead8042    ; Nope, so dead
        MOV     AL,0D1h          ; Program data port
        OUT     64h,AL           ; (to control port)
        CALL    Wait8042    ; Wait to accept command
        JNZ     SHORT Dead8042    ; Nope, so dead
        MOV     AL,AH            ; Value to program
        OUT     60h,AL           ; (to data port)

Wait8042:
        XOR     CX,CX            ; Plenty long enough!

Loop8042:
        IN      AL,64h           ; Get current state
        AND     AL,2             ; Busy?
        LOOPNZ  Loop8042        ; Yep, so keep waiting

Dead8042:
        RET                    ; No longer.
GateA20  ENDP

RealSeg  ENDS

```

```

;=====
;
; Protected mode code segment (still USE16). Used on initial start in
; protected mode, to initialise all tasks, then again to return to DOS.
;
ProtSeg    SEGMENT    PARA USE16

            ASSUME     CS:ProtSeg,DS:Nothing,ES:Nothing,FS:Nothing,GS:Nothing

ProtMode:
    CLI                                ; Not ready yet!
    MOV     AX,OFFSET MainStack        ; Reload SS under protected mode
    MOV     SS,AX
    MOV     ESP,OFFSET StackTop        ; Available!

    PUSH    LARGE 2                    ; All special bits zero
    POPFD                                     ; In flags register

;
; Reprogram Peripheral Interrupt Controllers (PICs) to move them out of the
; way of the Intel-reserved interrupts.
;
    MOV     AL,11h                      ; Initialise PICs
    OUT     20h,AL
    OUT     0A0h,AL

    MOV     AL,20h                      ; PIC1 @ 20h
    OUT     21h,AL
    MOV     AL,28h                      ; PIC2 @ 28h
    OUT     0A1h,AL

    MOV     AL,00000100b                ; PIC1 has slave on IRQ2
    OUT     21h,AL
    MOV     AL,02h                      ; PIC2 is slaved on IRQ2
    OUT     0A1h,AL

    MOV     AL,1                        ; 80x86 mode
    OUT     21h,AL
    OUT     0A1h,AL

    MOV     AL,0                        ; Enable all interrupts
    OUT     21h,AL
    OUT     0A1h,AL

;
; Reprogram timer to speed up task switching.
;
    MOV     AX,ClockFreq/SecTick        ; Divisor

    OUT     40h,AL                      ; Low byte
    JMP     $+2                          ; (tap foot)
    MOV     AL,AH                        ; High byte
    OUT     40h,AL

    MOV     AX,OFFSET GDTData            ; Point to desired segments
    MOV     DS,AX
    ASSUME     DS:GDT                    ; And tell assembler!

    MOV     AX,OFFSET MSDOSData

    MOV     FS,AX
    ASSUME     FS:Data

    MOV     AX,OFFSET Screen
    MOV     ES,AX
    MOV     GS,AX

```

```

MOV     FS:[TaskLock],1          ; Disable task switching for now
MOV     FS:[LastTask],OFFSET MainTask ; Point to current last task

MOV     AX,0700h+' '            ; Grey space
XOR     DI,DI                   ; Screen pointer
MOV     CX,2000                 ; 2000 screen locations
REP     STOSW                   ; Clear screen

STI                                     ; You can start now!

;
; Initialise remaining TSSs, in case a fault happens!
;
MOV     EAX,SEG TSS
SHL     EAX,4
MOV     BX,OFFSET MainTask
MOV     CX,OFFSET TSSSize
MOV     DL,Present+System+Gate386+AvailTSS
MOV     DH,ByteGran
CALL    AssignMem
LTR     BX                      ; Point Task Register to it

; Use memory above 1 Meg for TSS stacks
MOV     ESI,110000h            ; Point to memory above 1Mb+64K

MOV     EAX,SEG TSSDebug        ; Initialise Debug TSS
MOV     BX,OFFSET DebugTSS      ; Point to descriptor table entry
MOV     EBP,OFFSET DebugInt     ; Starting instruction to use
CALL    AssignTSS

MOV     EAX,SEG TSSDouble       ; Initialise Double TSS
MOV     BX,OFFSET DoubleTSS     ; Point to descriptor table entry
MOV     EBP,OFFSET DoubleInt    ; Starting instruction to use
CALL    AssignTSS

MOV     EAX,SEG TSSTSS          ; Initialise BadTSS TSS
MOV     BX,OFFSET BadTSSTSS     ; Point to descriptor table entry
MOV     EBP,OFFSET BadTSSInt    ; Starting instruction to use
CALL    AssignTSS

MOV     EAX,SEG BadStackTSS     ; Initialise BadStack TSS
MOV     BX,OFFSET StackTSS      ; Point to descriptor table entry
MOV     EBP,OFFSET StackInt     ; Starting instruction to use
CALL    AssignTSS

MOV     FS:[TaskLock],0        ; Can now enable task switching

; *** Insert any INT after this point ***
; (before this point I don't guarantee anything!)

;
; Now create each task
;
MOV     BX,OFFSET UserTasks-SIZE Descriptor
MOV     CX,(80/(WindowWidth+2))*(25/(WindowHeight+2)) ; No. tasks
TaskLoop:
PUSH    CX

; Allocate LDT
MOV     CX,OFFSET LDTLimit      ; Local descriptor table size
CALL    GetMem                  ; Allocate memory
MOV     DL,Present+Memory+Writable ; As data segment
MOV     DH,ByteGran
CALL    AssignMem                ; Modify GDT

; Initialise LDT
PUSH    DS

```

```

        PUSH    BX                      ; Save GDT pointer
        MOV     DS,BX                  ; Point to LDT
        MOV     BX,-SIZE Descriptor

; Allocate Stack0
        MOV     CX,StackSize-1          ; Size of stack
        CALL    GetMem                  ; Get Stack0
        MOV     DL,Present+Memory+Writable ; As data segment
        MOV     DH,ByteGran+More64k
        CALL    AssignMem                ; Modify LDT

; Allocate Stack3
        MOV     CX,StackSize-1          ; Size of stack
        CALL    GetMem                  ; Get Stack3
        MOV     DL,Present+Privilege3+Memory+Writable ; As data segment
        MOV     DH,ByteGran+More64k
        CALL    AssignMem                ; Modify LDT

; Point to user code
        MOV     EAX,SEG BallCode         ; Code segment
        SHL     EAX,4                    ; As linear address
        ADD     BX,SIZE Descriptor       ; Next descriptor
        MOV     CX,OFFSET CodeLimit      ; Bytes of code
        MOV     DL,Present+Privilege3+Memory+Execable+Readable ; As code
        MOV     DH,ByteGran+LargeAddr
        CALL    AssignMem                ; Modify LDT

; Allocate user data
        MOV     CX,OFFSET DataLimit      ; Size of data
        CALL    GetMem                  ; Get TaskData
        MOV     DL,Present+Privilege3+Memory+Writable ; As data segment
        MOV     DH,ByteGran
        CALL    AssignMem                ; Modify LDT

        POP     BX                      ; Restore GDT pointer
        POP     DS
        ASSUME   DS:GDT                  ; So tell assembler

        MOV     [BX.DescType],Present+Privilege3+System+LDT ; Is now LDT!

;
; Initialise TaskData to maintain uniqueness
; To pre-initialise data, access is needed to the two variables that define
; the window. To get this access requires loading a segment register. The
; descriptor for this segment is in the LDT for the task. So, temporarily
; point the LDT for the Main task to this LDT, load the segment register,
; and access the variables. BUT. The LDTR is NOT automatically saved on a
; task switch, and the LDT field in MainTask's TSS is zero, not this temporary
; LDT. So if any task switches happen in this critical region, on return a
; GP fault for ES will occur (points to a non-existent LDT!).
;
        CLI                      ; INTs can stuff up LDTR
        LLDT    BX                ; Use as LDT for now
        MOV     AX,OFFSET TaskData+LocalDT ; Point to allocated TaskData
        MOV     ES,AX              ; With ES
        ASSUME   ES:BallData       ; And tell assembler

        MOV     AX,FS:[Corner]      ; Get global corner
        MOV     ES:[Top],AH         ; Store as Top
        MOV     ES:[Left],AL        ; And Left

        XOR     AX,AX               ; Don't point to LDT
        MOV     ES,AX               ; with ES
        LLDT    AX                  ; anymore!
        STI                      ; LDTR safe again

        ADD     BYTE PTR FS:[Corner],WindowWidth+2 ; Next across
        CMP     BYTE PTR FS:[Corner],80-WindowWidth ; Too far?

```

```

        JB  SHORT AllocTSS                      ; Not yet
        ADD BYTE PTR FS:[Corner+1],WindowHeight+2 ; Yes, so next down
        MOV BYTE PTR FS:[Corner],1              ; And start again
AllocTSS:
        MOV     CX,TSSLimit                     ; Size of a TSS
        CALL    GetMem                          ; Get memory for TSS
        MOV     DL,Present+Memory+Writable      ; As a data segment
        MOV     DH,ByteGran
        CALL    AssignMem                       ; Modify GDT

        PUSH    DS
        PUSH    ES
        MOV     DS,BX                          ; Point to new segment
        MOV     ES,BX
        ASSUME  DS:TSS                        ; And tell (fool) assembler

        XOR     EAX,EAX                        ; Zero TSS
        XOR     DI,DI
        MOV     CX,TSSSize/4
        REP     STOSD

        MOV     [ESP0],StackSize               ; Initialise Stack0
        MOV     [SS0],OFFSET Stack0+LocalDT
        MOV     [EIPReg],OFFSET BallEntry      ; Entry point
        MOV     [EFlags],3202h                 ; IOPL = 3!
        MOV     [ESPReg],StackSize
        MOV     [CSSeg],OFFSET TaskCode+LocalDT+3 ; DPL=3 sets CPL
        MOV     [SSSeg],OFFSET Stack3+LocalDT+3 ; DPL=3
        MOV     [DSSeg],OFFSET TaskData+LocalDT+3 ; DPL=3
        MOV     [LDTR],BX                      ; LDT is current descriptor..
        SUB     [LDTR],SIZE Descriptor         ; ...minus 1
        MOV     [IOMapBase],TSSSize            ; No need to worry about I/O

        POP     ES                             ; Don't point to TSS any more
        POP     DS                             ; Restore GDT pointer
        ASSUME  DS:GDT                        ; So tell assembler

        MOV     [BX.DescType],Present+System+Gate386+AvailTSS ; Now a TSS!
        MOV     FS:[LastTask],BX               ; And can be switched to

        POP     CX                             ; Get task counter
        DEC     CX                             ; Any left?
        JNZ     TaskLoop                       ; Yes, so continue

        MOV     FS:[TaskLock],0                ; Can now start task switching
        AND     [MainTask.DescType],NOT Present ; But not here!
TaskEnd:
        JMP     TaskEnd                        ; Wait for keypress to leave

BackToDOS:
        CLI                                     ; Disable interrupts
; Same assembler problem: protected mode JMP
        DB     0EAh                            ; JMP FAR MSDOSCode:BackReal
        DW     OFFSET BackReal,OFFSET MSDOSCode

GetMem    PROC NEAR
        MOV     EAX,ESI                        ; New address
        MOVZX   ECX,CX                         ; Size to allocate
        ADD     ESI,ECX                        ; Allocated!
        AND     ESI,NOT 0FFh                   ; (Ensure on 256-byte boundary)
        ADD     ESI,100h                        ; And don't overlap!
        ADD     BX,SIZE Descriptor             ; New descriptor too
        RET
GetMem    ENDP

AssignMem PROC NEAR
        MOV     [BX.LimitLo],CX                ; Low limit
        MOV     [BX.BaseLo],AX                 ; Low base

```

```

        SHR      EAX,16                ; Get high base
        MOV      [BX.BaseMid],AL       ; Middle base
        MOV      [BX.DescType],DL     ; Type
        MOV      [BX.DescGran],DH     ; Granularity
        MOV      [BX.BaseHi],AH       ; High base (usually zero!)
        RET
AssignMem ENDP

AssignTSS PROC    NEAR
        SHL      EAX,4                ; Make address linear
        MOV      CX,OFFSET TSSLimit   ; Size of segment
        MOV      DL,Present+Memory+Writable ; Type to allocate
        MOV      DH,ByteGran
        CALL     AssignMem            ; Assign to descriptor

        PUSH     DS                   ; Point to TSS temporarily
        PUSH     ES
        MOV      DS,BX                ; (Note still a data descriptor)
        MOV      ES,BX
        ASSUME   DS:TSS              ; Tell (fool) assembler

        XOR      AX,AX                ; Zero TSS
        XOR      DI,DI
        MOV      CX,TSSSize/2
        REP      STOSW
        MOV      [EIPReg],EBP         ; Starting instruction
        MOV      [EFlags],0202h      ; Flags to use
        MOV      [ESPReg],OFFSET StackTop ; Stack pointer to use
        MOV      [CSSeg],OFFSET IntCode ; Code segment to use
        MOV      [SSSeg],BX          ; Stack to use
        ADD      [SSSeg],SIZE Descriptor ; (1 past TSS)
        MOV      [IOMapBase],TSSSize ; Don't worry about I/O
        POP      ES                   ; Don't point to TSS any more!
        POP      DS
        ASSUME   DS:GDT
        MOV      [BX.DescType],Present+System+Gate386+AvailTSS ; Now a TSS!

        MOV      CX,OFFSET StackTop   ; Allocated stack size
        CALL     GetMem                ; Next descriptor
        MOV      DL,Present+Memory+Writable ; Writable memory
        MOV      DH,ByteGran+More64k  ; 32-bit access
        CALL     AssignMem            ; Modify LDT
        RET
AssignTSS ENDP

ProtLimit EQU    $-1                  ; Limit of ProtSeg

ProtSeg    ENDS

```



ISE



İletiyi şu dile çevir: Türkçe



```

;=====
;
; User data and code. Note that code is set up for entry by initial values in
; TSS.

```

```

;
BallData SEGMENT PARA USE16
Top DB ?
Left DB ?
Bottom DB ?
Right DB ?
XLoc DB ?
YLoc DB ?
DeltaX DB ?
DeltaY DB ?
Counts DD ?
DataLimit EQU $-1
BallData ENDS

BallCode SEGMENT PARA USE32

        ASSUME CS:BallCode,DS:BallData,ES:Nothing,FS:Nothing,GS:Nothing

BallEntry PROC
        MOV     AX,OFFSET Screen        ; Point to screen
        MOV     ES,EAX                  ; With ES
        MOV     AL,[Top]                 ; Turn current Top
        MOV     [YLoc],AL               ; Into YLoc
        MOV     [Bottom],AL             ; And bottom
        ADD     [Bottom],WindowHeight-1 ; Shift bottom down
        DEC     AL                       ; Turn into memory address
        MOV     AH,80*2                  ; Row factor
        MUL     AH
        MOVZX   EBX,AX                   ; Into pointer

        MOVZX   EAX,[Left]               ; Get column
        MOV     [XLoc],AL                ; Into XLoc
        MOV     [Right],AL               ; And right
        ADD     [Right],WindowWidth-1    ; Shift right across
        DEC     EAX                      ; Turn into memory address
        SHL     EAX,1
        ADD     EBX,EAX                  ; Add into pointer

        MOV     EDI,EBX                  ; Get into STO pointer
        CALL    DrawFrame                ; And draw the frame
        ADD     EBX,2*80+2               ; First position in frame
        MOV     BYTE PTR ES:[EBX],Ball   ; Store ball into position
        MOV     [DeltaX],1               ; Head to the right
        MOV     [DeltaY],1               ; And head down
        MOV     [Counts],0               ; Count to time
        STD

Bounce:
        MOV     ECX,BounceTime           ; Wait to bounce
BounceDelay:
        LOOP    BounceDelay              ; (tap foot)

        MOV     EBP,EBX                  ; Old position

; Calculate new position
        MOV     AL,[YLoc]                 ; Get current YLoc
        ADD     AL,[DeltaY]               ; Add in Delta
        CMP     AL,[Top]                  ; Too high?
        JB      SHORT YWrap              ; Yes, so wrap
        CMP     AL,[Bottom]               ; Too low?
        JNA     SHORT NoYWrap            ; No, so don't wrap

YWrap:
        NEG     [DeltaY]                  ; Reverse direction
        ADD     AL,[DeltaY]               ; Undo mistake
        ADD     AL,[DeltaY]               ; Head properly!

NoYWrap:
        MOV     [YLoc],AL                ; Save away
        MOV     AH,80*2                  ; Row factor
        MUL     AH                       ; Turn into memory address

```

```

        MOVZX     EBX,AX                ; Into index register

        MOVZX     EAX,[XLoc]           ; Get current XLoc
        ADD       AL,[DeltaX]          ; Add in Delta
        CMP       AL,[Left]            ; Too left?
        JB  SHORT XWrap                ; Yes, so wrap
        CMP       AL,[Right]           ; Too right?
        JNA  SHORT NoXWrap             ; No, so don't wrap

XWrap:   NEG       [DeltaX]             ; Reverse direction
        ADD       AL,[DeltaX]          ; Undo mistake
        ADD       AL,[DeltaX]          ; Head properly!

NoXWrap: MOV       [XLoc],AL           ; Save away
        MOV       AH,0                ; Turn into memory address
        SHL       EAX,1               ; Column factor
        ADD       EBX,EAX              ; Add into memory address
        MOV  BYTE PTR ES:[EBP], ' '    ; Delete old ball
        MOV  WORD PTR ES:[EBX],0F00h+Ball ; Paint new ball
        JMP       Bounce               ; And bounce forever!

BallEntry ENDP

DrawFrame PROC     NEAR
        XOR       ECX,ECX              ; Zero high part of ECX
        MOV       AH,0Fh               ; White background
        MOV       AL,'Ú'               ; TopLeft corner
        STOSW                      ; Store on screen
        MOV       AL,'Ä'               ; Top
        MOV       CL,WindowWidth       ; This many
        REP       STOSW               ; Store on screen
        MOV       AL,'¿'               ; TopRight corner
        STOSW                      ; Store on screen
        ADD       EDI,2*(80-WindowWidth-2) ; Next row
        MOV       CL,WindowHeight      ; Height
        JCXZ      NoSide               ; None!

Side:   PUSH      ECX                  ; Need this later
        MOV       AL,'³'               ; A side
        STOSW                      ; Store on screen
        MOV       AL,' '               ; Blank
        MOV       CL,WindowWidth       ; This many
        REP       STOSW               ; Store on screen
        MOV       AL,'³'               ; Other side
        STOSW                      ; Store on screen
        ADD       EDI,2*(80-WindowWidth-2) ; Next row
        POP       ECX                  ; Restore row count
        LOOP      Side

NoSide: MOV       AL,'À'               ; Bottom left
        STOSW                      ; Store on screen
        MOV       AL,'Ä'               ; Bottom
        MOV       CL,WindowWidth       ; This many
        REP       STOSW               ; Store on screen
        MOV       AL,'Û'               ; Bottom right
        STOSW                      ; Store on screen
        RET

DrawFrame ENDP

CodeLimit EQU     $-1

BallCode  ENDS

```

```

;=====
;
; This segment is for interrupt code. As well as the hardware interrupt
; handlers, there is also code to handle the various faults. Most of the
; code simply displays all of the registers' contents, then bombs back to

```

```

; DOS. The timer and keyboard interrupt, however, is actually used.
; Note this segment is marked as being USE32. This was both as an experiment,
; and also because most instructions used will be 32-bit instructions, since
; I want to be able to display all of each register.
;
IntSeg      SEGMENT      PARA USE32

              ASSUME      CS:IntSeg,DS:Nothing,ES:Nothing,FS:Nothing,GS:Nothing

DivideInt:
    PUSH      0              ; Pseudo-error code
    PUSH      0              ; INT 0
    JMP        Interrupt     ; Show registers

;
; Simple code. Entered on single step interrupt, waits for Enter or Space,
; then returns. Note dingle<tm> in top right corner indicates 'waiting'.
; Pressing Enter stops the single-step action
;
DebugInt    PROC
    PUSH      EBX              ; Need these registers
    PUSH      DS
    PUSH      ES
    MOV        BX,OFFSET MSDOSData ; Point to Data
    MOV        DS,EBX

    ASSUME      DS:Data        ; And tell assembler

    MOV        BX,OFFSET Screen ; Point to screen
    MOV        ES,EBX
    STI

KeyLoop:
    INC BYTE PTR ES:[009Eh]    ; Dingle<tm> screen location
    CMP        [KeyPress],57   ; Space pressed?
    JE         SHORT EndDebug   ; Yes, so leave
    CMP        [KeyPress],28   ; Enter pressed?
    JNE        KeyLoop         ; No, so keep waiting
    AND WORD PTR [ESP+14h],NOT 100h ; Yes, so stop tracing

EndDebug:
    MOV        [KeyPress],0     ; Key? What key?
    POP        ES
    POP        DS
    POP        EBX
    IRETD                ; Return from task
    JMP        DebugInt        ; Re-entry will appear here

DebugInt    ENDP

;
; If above not required, use this instead (modify IDT).
;
BadDebugInt:
    PUSH      0              ; Pseudo-error code
    PUSH      1              ; INT 1
    JMP        InterTask      ; Get values from TSS

NMIInt:
    PUSH      0              ; Pseudo-error code
    PUSH      2              ; INT 2
    JMP        Interrupt     ; Display registers

BreakInt:
    PUSH      0              ; Pseudo-error code
    PUSH      3              ; INT 3
    JMP        Interrupt     ; Display registers

OverInt:
    PUSH      0              ; Etcetera
    PUSH      4              ; Etcetera
    JMP        Interrupt     ; Etcetera

BoundInt:

```

```

        PUSH    0
        PUSH    5
        JMP     Interrupt
OpInt:
        PUSH    0
        PUSH    6
        JMP     Interrupt
No387Int:
        PUSH    0
        PUSH    7
        JMP     Interrupt
DoubleInt:
        PUSH    31
        JMP     InterTask
; Note no pseudo-error code, as
; Double Faults have a real one
Over387Int:
        PUSH    0
        PUSH    9
        JMP     Interrupt
BadTSSInt:
        PUSH    10
        JMP     InterTask
; Note no pseudo-error code
; Display registers from TSS
NoSegInt PROC
        PUSH    EBX
        PUSH    DS
        MOV     BX,OFFSET Screen
        MOV     DS,EBX
        INC     BYTE PTR DS:[0014h]
; Indicate on screen

        MOV     BX,OFFSET GDTData
        MOV     DS,EBX
        ASSUME  DS:GDT
        MOV     BX,[ESP+8]
        AND     BX,NOT 07h
        OR      [BX.DescType],Present
        POP     DS
        POP     EBX
        ADD     ESP,4
; Ignore error code
; And restart instruction
NoSegInt ENDP

StackInt:
        PUSH    12
        JMP     InterTask
; Note no pseudo-error code
; Display registers from TSS
GenInt:
        PUSH    13
        JMP     Interrupt
; Note no pseudo-error code
PageInt:
        PUSH    14
        JMP     Interrupt
; Note no pseudo-error code
Int15:
        PUSH    0
        PUSH    15
        JMP     Interrupt
; Push pseudo-error code
Bad387Int:
        PUSH    0
        PUSH    16
        JMP     Interrupt
Int17:
        PUSH    0
        PUSH    17
        JMP     Interrupt
Int18:
        PUSH    0
        PUSH    18
        JMP     Interrupt
Int19:

```

```

Int20:  PUSH    0
        PUSH    19
        JMP     Interrupt

Int21:  PUSH    0
        PUSH    20
        JMP     Interrupt

Int22:  PUSH    0
        PUSH    21
        JMP     Interrupt

Int23:  PUSH    0
        PUSH    22
        JMP     Interrupt

Int24:  PUSH    0
        PUSH    23
        JMP     Interrupt

Int25:  PUSH    0
        PUSH    24
        JMP     Interrupt

Int26:  PUSH    0
        PUSH    25
        JMP     Interrupt

Int27:  PUSH    0
        PUSH    26
        JMP     Interrupt

Int28:  PUSH    0
        PUSH    27
        JMP     Interrupt

Int29:  PUSH    0
        PUSH    28
        JMP     Interrupt

Int30:  PUSH    0
        PUSH    29
        JMP     Interrupt

Int31:  PUSH    0
        PUSH    30
        JMP     Interrupt

Int31:  PUSH    0
        PUSH    31
        JMP     Interrupt

```

```

TimerInt PROC
        PUSH    EAX                ; Need these registers
        PUSH    EBX
        PUSH    DS
        PUSH    ES
        MOV     AL, 20h           ; Acknowledge interrupt in PIC

```

```

        OUT        20h,AL                ; (Note interrupts still off)

        MOV        AX,OFFSET MSDOSData    ; Point to Data
        MOV        DS,EAX
        ASSUME     DS:Data                ; And tell assembler

        CMP        [TaskLock],0           ; Task switching locked out?
        JNE SHORT  NoSwitch               ; Yes, so do nothing

        MOV        AX,OFFSET GDTData      ; Point to GDT alias
        MOV        ES,EAX
        ASSUME     ES:GDT                 ; And tell assembler

        STR        AX                     ; Get current task number
        MOVZX      EBX,AX                  ; Into index pointer

TestTask:
        ADD        EBX,SIZE Descriptor    ; Look at next descriptor
        CMP        BX,[LastTask]          ; Too far?
        JBE SHORT  NotEndGDT              ; Not yet
        MOV        EBX,OFFSET MainTask    ; Yes, so start again

NotEndGDT:
        CMP        BX,AX                  ; Back here again?
        JE SHORT   NoSwitch               ; Yes, so none to switch to
        CMP BYTE PTR ES:[EBX.DescType],Present+Gate386+AvailTSS ; Is TSS?
        JNE        TestTask               ; No, so keep looking

        MOV        [NextTask],BX          ; New task!
        JMP        [TaskJump]              ; So jump to it (task switching)

NoSwitch:
        POP        ES
        POP        DS                     ; When jumps back, continues here
        POP        EBX
        POP        EAX

TimerInt IRETD                           ; So return where you left off
        ENDP

KeyInt   PROC
        PUSH      EAX                     ; Need these registers
        PUSH      DS
        MOV        AX,OFFSET MSDOSData    ; Point to data
        MOV        DS,EAX

        ASSUME     DS:Data                ; And tell assembler

        MOV        AL,20h                 ; Acknowledge PIC
        OUT        20h,AL                 ; (Note interrupts still off)
        IN         AL,60h                 ; Get character from keyboard
        MOV        [KeyPress],AL          ; Store in global data
        CMP        [KeyPress],129         ; Is it Esc released?
        JE         IntDOS                 ; Yes, so back to DOS!
        POP        DS                     ; No, so continue
        POP        EAX

        IRETD
KeyInt   ENDP


SlaveInt:
        PUSH      0                       ; Pseudo-error code
        PUSH      34                       ; Note this interrupt is not
        JMP SHORT  IRQ                     ; possible - it is the cascade.

COM2Int:
        PUSH      0
        PUSH      35

```

```

COM1Int:    JMP SHORT IRQ                    ; Acknowledge PIC1
            PUSH     0
            PUSH     36
            JMP SHORT IRQ

IRQ5:       PUSH     0
            PUSH     37
            JMP SHORT IRQ

IRQ6:       PUSH     0
            PUSH     38
            JMP SHORT IRQ

PrintInt:   PUSH     0
            PUSH     39
            JMP SHORT IRQ

IRQ8:       PUSH     0
            PUSH     40
            JMP SHORT IRQB                  ; Acknowledge PIC2

IRQ9:       PUSH     0
            PUSH     41
            JMP SHORT IRQB

IRQ10:      PUSH     0
            PUSH     42
            JMP SHORT IRQB

IRQ11:      PUSH     0
            PUSH     43
            JMP SHORT IRQB

IRQ12:      PUSH     0
            PUSH     44
            JMP SHORT IRQB

IRQ13:      PUSH     0
            PUSH     45
            JMP SHORT IRQB

IRQ14:      PUSH     0
            PUSH     46
            JMP SHORT IRQB

IRQ15:      PUSH     0
            PUSH     47

IRQB:       PUSH     EAX                    ; Acknowledge PIC2
            MOV     AL, 20h
            OUT     0A0h, AL
            POP     EAX

IRQ:        PUSH     EAX                    ; Acknowledge PIC1
            MOV     AL, 20h
            OUT     20h, AL
            POP     EAX

Interrupt PROC
            PUSHAD                    ; Save all registers
            PUSH     DS
            PUSH     ES
            PUSH     FS
            PUSH     GS
            PUSH     SS
            STR      AX                ; Including faulting task

```

```

        PUSH    EAX
        PUSH    CS
        POP     DS                ; Point to code, for strings

        MOV     AX,OFFSET Screen    ; Point to screen
        MOV     ES,EAX
        MOV     ESI,OFFSET RegNames ; Point to strings
        MOV     EDI,[ESP+56]        ; Interrupt number on stack here
;        SHL     EDI,1                ; Turn into screen address
;        INC     BYTE PTR ES:[EDI]    ; One of these!
        MOV     AX,OFFSET MSDOSData ; Point to data
        MOV     FS,EAX
        MOV     FS:[TaskLock],1    ; Stop task switching!
        STI
        MOV     AH,4Fh              ; White-on-red!
        AND     EDI,NOT 0Fh         ; Position to tab-stop
        ADD     EDI,160             ; On next row
DumpRegs:
        CLD                        ; Work forwards
        MOV     ECX,5               ; Five characters of text
NameLoop:
        LODSB                      ; Get character
        STOSW                      ; Store attrib+char
        LOOP    NameLoop           ; For each character
        LODSB                      ; Get size of register
        MOV     CL,AL              ; Into counter
        LODSB                      ; Get position on stack
        MOVZX   EBX,AL             ; Into offset
        LODSB                      ; Get rid of position in TSS
        MOV     EDX,[ESP+EBX]      ; Get value from stack
        CALL    Hex                ; Display as hex
NoData:
        ADD     EDI,160            ; Start new row
        AND     EDI,NOT 0Fh        ; At tab-stop
        CMP     ESI,OFFSET EndRegs ; End of registers?
        JB      DumpRegs           ; No, so continue
        CMP     BYTE PTR [ESP+56],32 ; Was it a hardware int?
        JAE     SHORT EndInt       ; Yes, so continue
IntDOS:
        CLI                        ; No, so back to DOS!
        DB      0EAh               ; JMP FAR ProtCode:BackToDOS
        DD      OFFSET BackToDOS,OFFSET ProtCode
EndInt:
        ADD     ESP,8              ; Ignore saved TR and SS
        POP     GS                 ; Pop everything else
        POP     FS
        POP     ES
        POP     DS
        POPAD
        ADD     ESP,8              ; Ignore int number and error code
        IRETD                      ; And return
Interrupt ENDP

```

```

InterTask PROC
        MOV     AX,OFFSET MSDOSData ; Point to data
        MOV     DS,EAX

        ASSUME  DS:Data             ; And tell assembler

        MOV     [TaskLock],1        ; Stop task switching!

```

```

MOV     AX,OFFSET Screen      ; Point to screen
MOV     ES,EAX
ASSUME  ES:Nothing

MOV     AX,OFFSET GDTData    ; Point to GDT
MOV     FS,EAX
ASSUME  FS:GDT

STR     BX                    ; Get current task
MOV     FS:[BX.DescType],Present+Memory ; Turn it into memory
MOV     GS,EBX                ; Load into segment reg

ASSUME  GS:TSS                ; And tell (fool) assembler

MOVZX   EBX,GS:[BackLink]    ; Get BackLink TSS
CMP     EBX,0
JE      SHORT NotLinked
MOV     FS:[EBX.DescType],Present+Memory+Writable ; Make writable
MOV     GS,EBX                ; Load into segment reg
MOV     GS:[BackLink],BX     ; Store this TR somewhere
NotLinked:
PUSH    CS                    ; Point to strings
POP      DS
MOV     ESI,OFFSET RegNames  ; Point to strings
MOV     EDI,[ESP]             ; Position screen pointer
SHL     EDI,1
AND     EDI,NOT 0Fh
INC     BYTE PTR ES:[EDI]
ADD     EDI,80*2
Name2Loop:
CLD                                ; Work forwards
MOV     AH,4Fh                 ; White-on-red!
MOV     ECX,5                  ; Five characters per string
CharLoop:
LODSB                    ; Get character
STOSW                    ; Store character+attribute
LOOP    CharLoop          ; Once for each char
LODSB                    ; Get length of data
MOV     CL,AL              ; Into counter
LODSB                    ; Ignore position on stack
LODSB                    ; Get position in TSS
MOVZX   EBX,AL             ; Into Index register
MOV     EDX,GS:[EBX]       ; Get value
CMP     AL,8               ; Is it int number?
JA      SHORT HexIt        ; No, so hex it
CMP     AL,0               ; Is it task number?
JE      SHORT HexIt        ; Yes, so hex it
MOV     EDX,[ESP+EBX-4]     ; No, so fish off stack
HexIt:
CALL    Hex                ; Display it
ADD     EDI,160             ; Go to next row
AND     EDI,NOT 0Fh         ; To previous tab-stop
CMP     ESI,OFFSET EndTSSRegs ; End of registers?
JB      Name2Loop          ; Not yet

JMP     IntDOS              ; Yes, so leave
InterTask ENDP

Hex      PROC      NEAR
STD                                ; Work backwards
LEA     EDI,[EDI+ECX*2-2]    ; Point to end of number
HexLoop:
MOV     AL,DL               ; Get lowest byte
AND     AL,0Fh              ; Isolate low nybble
ADD     AL,'0'              ; Turn into ASCII
CMP     AL,'9'              ; Too far?

```

```

        JBE SHORT LoopHex          ; No
        ADD     AL, 'A' - '9' - 1  ; Yes, so turn into hex
LoopHex:
        STOSW                      ; Store
        SHR     EDX, 4              ; Shift in next nybble
        LOOP    HexLoop            ; Loop
        RET                               ; And return
Hex
        ENDP

RegNames DB      'Int: ', 2, 56, 4          ; Name, width, stack pos, TSS pos
        DB      'EAX: ', 8, 52, 40
        DB      'EBX: ', 8, 40, 52
        DB      'ECX: ', 8, 48, 44
        DB      'EDX: ', 8, 44, 48
        DB      'ESI: ', 8, 28, 64
        DB      'EDI: ', 8, 24, 68
        DB      'ESP: ', 8, 36, 56
        DB      'EBP: ', 8, 32, 60
        DB      'EIP: ', 8, 64, 32
        DB      'Flag: ', 8, 72, 36
        DB      'CS: ', 4, 68, 76
        DB      'DS: ', 4, 20, 84
        DB      'ES: ', 4, 16, 72
        DB      'FS: ', 4, 12, 88
        DB      'GS: ', 4, 8, 92
        DB      'SS: ', 4, 4, 80
        DB      'Task: ', 4, 0, 0
        DB      'Err: ', 4, 60, 8
EndRegs EQU $
        DB      'LDT: ', 4, -1, 96
EndTSSRegs EQU $

IntLimit EQU $-1

IntSeg    ENDS

        END      Entry

```